* The extra capacitor at the regulator? (Optional)
* The two grounds at pins 22 and 23 at the IMU?
* Don’t have to have pins for unconnected pins of the microcontroller?
* Jump Capacitors should be 0Ohm resistors
* The antenna circuit connect directly to the controller so when working on the board layout you will see on the circuit what should be physically close to the microcontroller.
* Power of the motor should come directly from the battery instead of 3V regulated voltage.
* Make pads of the NMOS bigger for transferring the heat better.